

intended coverage sector, where required, to specifically prevent invalid removal of an airborne warning indication in the presence of misleading guidance information.

Path Following Error (PFE) means the guidance perturbations which could cause aircraft displacement from the desired course or glidepath. It is composed of the path following noise and of the mean course error in the case of azimuth functions, or the mean glidepath error in the case of elevation functions. Path following errors are evaluated by filtering the flight error record with a second order low pass filter which has a corner frequency at 0.5 radian/sec for azimuth data or 1.5 radians/sec for elevation data.

Path following noise (PFN) means that portion of the guidance signal error which could cause displacement from the actual mean course line or mean glidepath as appropriate.

Split-site ground station means the type of ground station in which the azimuth portion of the ground station is located near the stop end of the runway, and the elevation portion is located near the approach end.

Time division multiplex (TDM) means that each function is transmitted on the same frequency in time sequence, with a distinct preamble preceding each function transmission.

§ 171.305 Requests for IFR procedure.

(a) Each person who requests an IFR procedure based on an MLS facility which that person owns must submit the following information with that request:

(1) A description of the facility and evidence that the equipment meets the performance requirements of §§ 171.309, 171.311, 171.313, 171.315, 171.317, 171.319, and 171.321 and is fabricated and installed in accordance with § 171.323.

(2) A proposed procedure for operating the facility.

(3) A proposed maintenance organization and a maintenance manual that meets the requirements of § 171.325.

(4) A statement of intent to meet the requirements of this subpart.

(5) A showing that the facility has an acceptable level of operational reliability and an acceptable standard of performance. Previous equivalent oper-

ational experience with a facility with identical design and operational characteristics will be considered in showing compliance with this subparagraph.

(b) FAA inspects and evaluates the MLS facility; it advises the owner of the results, and of any required changes in the MLS facility or in the maintenance manual or maintenance organization. The owner must then correct the deficiencies, if any, and operate the MLS facility for an in-service evaluation by the FAA.

§ 171.307 Minimum requirements for approval.

(a) The following are the minimum requirements that must be met before the FAA approves an IFR procedure for a non-Federal MLS facility:

(1) The performance of the MLS facility, as determined by flight and ground inspection conducted by the FAA, must meet the requirements of §§ 171.309, 171.311, 171.313, 171.315, 171.317, 171.319, and 171.321.

(2) The fabrication and installation of the equipment must meet the requirements of § 171.323.

(3) The owner must agree to operate and maintain the MLS facility in accordance with § 171.325.

(4) The owner must agree to furnish operational records as set forth in § 171.327 and agree to allow the FAA to inspect the facility and its operation whenever necessary.

(5) The owner must assure the FAA that he will not withdraw the MLS facility from service without the permission of the FAA.

(6) The owner must bear all costs of meeting the requirements of this section and of any flight or ground inspection made before the MLS facility is commissioned.

(b) [Reserved]

§ 171.309 General requirements.

The MLS is a precision approach and landing guidance system which provides position information and various ground-to-air data. The position information is provided in a wide coverage sector and is determined by an azimuth angle measurement, an elevation angle measurement and a range (distance) measurement.

(a) An MLS constructed to meet the requirements of this subpart must include:

(1) Approach azimuth equipment, associated monitor, remote control and indicator equipment.

(2) Approach elevation equipment, associated monitor, remote control and indicator equipment.

(3) A means for the encoding and transmission of essential data words, associated monitor, remote control and indicator equipment. Essential data are basic data words 1, 2, 3, 4, and 6 and auxiliary data words A1, A2 and A3.

(4) Distance measuring equipment (DME), associated monitor, remote control and indicator equipment.

(5) Remote controls for paragraphs (a) (1), (2), (3), and (4) of this section must include as a minimum on/off and reset capabilities and may be integrated in the same equipment.

(6) At locations where a VHF marker beacon (75 MHz) is already installed, it may be used in lieu of the DME equipment.

(b) In addition to the equipment required in paragraph (a) of this section the MLS may include:

(1) Back azimuth equipment, associated monitor, remote control and indicator equipment. When Back Azimuth is provided, a means for transmission of Basic Data Word 5 and Auxiliary Data Word A4 shall also be provided.

(2) A wider proportional guidance sector which exceeds the minimum specified in §§ 171.313 and 171.317.

(3) Precision DME, associated monitor, remote control and indicator equipment.

(4) VHF marker beacon (75 MHz), associated monitor, remote control and indicator equipment.

(5) The MLS signal format will accommodate additional functions (e.g., flare elevation) which may be included as desired. Remote controls for paragraphs (b) (1), (3) and (4) of this section must include as a minimum on/off and reset capabilities, and may be integrated in the same equipment.

(6) Provisions for the encoding and transmission of additional auxiliary data words, associated monitor, remote control and indicator equipment.

(c) MLS ground equipment must be designed to operate on a nominal 120/

240 volt, 60 Hz, 3-wire single phase AC power source and must meet the following service conditions:

(1) AC line parameters, DC voltage, elevation and duty:

120 VAC nominal value—102 V to 138 V (± 1 V)*

240 VAC nominal value—204 V to 276 V (± 2 V)*

60 Hz AC line frequency—57 Hz to 63 Hz (± 0.2 Hz)*

*NOTE: Where discrete values of the above frequency or voltages are specified for testing purposes, the tolerances given in parentheses indicated by an asterisk apply to the test instruments used to measure these parameters.

Elevation—0 to 3000 meters (10,000 feet) above sea level

Duty—Continuous, unattended

(2) Ambient conditions within the shelter for electronic equipment installed in shelters are:

Temperature, -10°C to $+50^{\circ}\text{C}$

Relative humidity, 5% to 90%

(3) Ambient conditions for electronic equipment and all other equipment installed outdoors (for example, antenna, field detectors, and shelters):

Temperature, -50°C to $+70^{\circ}\text{C}$

Relative humidity, 5% to 100%

(4) All equipment installed outdoors must operate satisfactorily under the following conditions:

Wind Velocity: The ground equipment shall remain within monitor limits with wind velocities of up to 70 knots from such directions that the velocity component perpendicular to runway centerline does not exceed 35 knots. The ground equipment shall withstand winds up to 100 knots from any direction without damage.

Hail Stones: 1.25 centimeters ($\frac{1}{2}$ inch) diameter.

Rain: Provide required coverage with rain falling at a rate of 50 millimeters (2 inches) per hour, through a distance of 9 kilometers (5 nautical miles) and with rain falling at the rate of 25 millimeters (1 inch) per hour for the additional 28 kilometers (15 nautical miles).

Ice Loading: Encased in 1.25 centimeters ($\frac{1}{2}$ inch) radial thickness of clear ice.

Antenna Radome De-Icing: Down to -6°C (20°F) and wind up to 35 knots.

(d) The transmitter frequencies of an MLS must be in accordance with the frequency plan approved by the FAA.

(e) The DME component listed in paragraph (a)(4) of this section must comply with the minimum standard performance requirements specified in subpart G of this part.

(f) The marker beacon components listed in paragraph (b)(4) of this section must comply with the minimum standard performance requirements specified in subpart H of this part.

§ 171.311 Signal format requirements.

The signals radiated by the MLS must conform to the signal format in which angle guidance functions and data functions are transmitted sequentially on the same C-band frequency. Each function is identified by a unique digital code which initializes the airborne receiver for proper processing. The signal format must meet the following minimum requirements:

(a) *Frequency assignment.* The ground components (except DME/Marker Beacon) must operate on a single frequency assignment or channel, using time division multiplexing. These components must be capable of operating on any one of the 200 channels spaced 300 KHz apart with center frequencies from 5031.0 MHz to 5090.7 MHz and with channel numbering as shown in Table 1a. The operating radio frequencies of all ground components must not vary

by more than ± 10 KHz from the assigned frequency. Any one transmitter frequency must not vary more than ± 50 Hz in any one second period. The MLS angle/data and DME equipment must operate on one of the paired channels as shown in Table 1b.

TABLE 1a—FREQUENCY CHANNEL PLAN

| Channel No. | Frequency (MHz) |
|-------------|-----------------|
| 500 | 5031.0 |
| 501 | 5031.3 |
| 502 | 5031.6 |
| 503 | 5031.9 |
| 504 | 5032.2 |
| 505 | 5032.5 |
| 506 | 5032.8 |
| 507 | 5033.1 |
| 508 | 5033.4 |
| 509 | 5033.7 |
| 510 | 5034.0 |
| 511 | 5034.3 |
| * | * |
| 598 | 5060.4 |
| 599 | 5060.7 |
| 600 | 5061.0 |
| 601 | 5061.3 |
| * | * |
| 698 | 5090.4 |
| 699 | 5090.7 |

TABLE 1b—CHANNELS

| Channel pairing | | | | DME parameters | | | | | |
|-----------------|---------------|---------------------|-------------|----------------|---------------|------------------------------------------|-----------|-------------|---------|
| DME No. | VHF freq. MHz | MLS angle freq. MHz | MLS Ch. No. | Interrogation | | | Reply | | |
| | | | | Freq. MHz | Pulse codes | | Freq. MHz | Pulse codes | |
| | | | | | DME/N μ s | DME/P Mode IA μ s FA μ s | | | μ s |
| * 1X | | | | 1025 | 12 | | 962 | 12 | |
| ** 1Y | | | | 1025 | 36 | | 1088 | 30 | |
| * 2X | | | | 1026 | 12 | | 963 | 12 | |
| ** 2Y | | | | 1026 | 36 | | 1089 | 30 | |
| * 3X | | | | 1027 | 12 | | 964 | 12 | |
| ** 3Y | | | | 1027 | 36 | | 1090 | 30 | |
| * 4X | | | | 1028 | 12 | | 965 | 12 | |
| ** 4Y | | | | 1028 | 36 | | 1091 | 30 | |
| * 5X | | | | 1029 | 12 | | 966 | 12 | |
| ** 5Y | | | | 1029 | 36 | | 1092 | 30 | |
| * 6X | | | | 1030 | 12 | | 967 | 12 | |
| ** 6Y | | | | 1030 | 36 | | 1093 | 30 | |
| * 7X | | | | 1031 | 12 | | 968 | 12 | |
| ** 7Y | | | | 1031 | 36 | | 1094 | 30 | |
| * 8X | | | | 1032 | 12 | | 969 | 12 | |
| ** 8Y | | | | 1032 | 36 | | 1095 | 30 | |
| * 9X | | | | 1033 | 12 | | 970 | 12 | |
| ** 9Y | | | | 1033 | 36 | | 1096 | 30 | |
| * 10X | | | | 1034 | 12 | | 971 | 12 | |
| ** 10Y | | | | 1034 | 36 | | 1097 | 30 | |
| * 11X | | | | 1035 | 12 | | 972 | 12 | |